



Stabilization Of Programmed Motion

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Stabilization Of Programmed Motion:

Stabilization of Programmed Motion E Ya Smirnov, 2000-09-20 This volume presents a particular aspect of control theory stabilization of programmed motion Methods of the construction and synthesis of stabilizing controls are introduced together with original results and useful examples The problem of optimal stabilization control synthesis is solved for linear systems of difference equations with quadratic

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cover a wide class of classical objects in theoretical mechanics and primarily solid body robotic gyroscopic rocket cosmic and other systems And what is rather important they have a direct trend to practical application To indicate this discussion I should like to notice that it does not touch upon the questions concerned with the linear and stochastic control objects Investigated are only nonlinear deterministic systems being in the conditions when some system parameters are either unknown or beyond the reach of measurement or they execute an unknown limited and fairly smooth drift in time

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